

## Learning Boolean Networks from ToxCast High-Content Imaging Data

### **Todor Antonijevic**

ORCID ID 0000-0002-0248-8412

The views expressed in this presentation are those of the author[s] and do not necessarily reflect the views or policies of the U.S. Environmental Protection Agency.

**SEPA**



I. Introduction

### II. Methods:

- 1. Dataset
- 2. Data standardization, and Noise Threshold  $(z_0)$ .
- 3. Data Discretization.
- 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).
- 5. Needleman-Wunsch (NW) optimal global alignment, and Error Estimation.
- 6. Coverage.

### III. Results:

- 1. Discretized Trajectories and Total Perturbation.
- 2. Clustering of discretized trajectories, Error Estimation, and Coverage (first 10 BNs).
- 3. Learned BNs in case of Butachlor.

### **IV.** Summary

**\$EPA** 



I. Introduction

#### II. Methods:

- 1. Dataset
- 2. Data standardization, and Noise Threshold  $(z_0)$ .
- 3. Data Discretization.
- 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).
- 5. Needleman-Wunsch (NW) optimal global alignment, and Error Estimation.
- 6. Coverage.

### III. Results:

- 1. Discretized Trajectories and Total Perturbation.
- 2. Clustering of discretized trajectories, Error Estimation, and Coverage (first 10 BNs).
- 3. Learned BNs in case of Butachlor.

### **IV.** Summary



Networks



## SEPA Introduction



Krewski, Daniel, et al. "Toxicity testing in the 21st century: a vision and a strategy." Journal of Toxicology and Environmental Health, Part B 13.2-4 (2010): 51-138.

- "Tipping point" system threshold between adaptation and adversity.
- Boolean networks (BN) are logical models of integrated cellular response pathways
- Here we reconstruct simple BN using high-content imaging data to analyze cellular tipping points

5

**\$EPA** 



I. Introduction

#### II. Methods:

- 1. Dataset
- **2.** Data standardization, and Noise Threshold  $(z_0)$ .
- 3. Data Discretization.
- 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).
- 5. Needleman-Wunsch (NW) optimal global alignment, and Error Estimation.
- 6. Coverage.

### III. Results:

- 1. Discretized Trajectories and Total Perturbation.
- 2. Clustering of discretized trajectories, Error Estimation, and Coverage (first 10 BNs).
- 3. Learned BNs in case of Butachlor.

### **IV.** Summary





**EPA** 

#### Dataset:

HCI data<sup>1</sup> were used to study the effect of 967 ToxCast chemicals on HepG2 cell states by monitoring:

- **10 endpoints** across
- multiple time points:

**ToxCast I:** 1, 24, and 72h, ToxCast II: 24 and 72h

**10 concentrations** (0.4 to 200µM).



### 1. Dataset - High Content Imaging (HCI)

• Image analysis and cell level features are conducted by Cyprotex Inc.





- The following cellular endpoints were quantified:
  - 1. phosphorylated p53 / p53 activation (p53),
  - 2. phosphorylated c-Jun/c-Jun activation (SK),
  - 3. phospho-Histone H2A.x (OS),
  - 4. phospho-Histone H3 / mitotic arrest (MA),
  - 5. phosphorylated  $\alpha$ -tubulin / microtubules (**Mt**),
  - 6. mitochondrial membrane potential (MMP),
  - 7. mitochondrial mass (MM),
  - 8. cell cycle arrest (CCA),
  - 9. nuclear size (NS), and
  - 10. cell number (CN).



### 2. Data standardization, and Noise Threshold $(z_0)$ .

Data standardization:

 $z = \frac{x - x^*}{\sigma_x}$ 

- $x \log_2$  transformed fold change
- $x^*$  the median value
- $\sigma_x$  the standard deviation

### Noise Threshold $z_0$ :



## **SEPA** 3. Data Discretization.

#### Motivation: Increase of p53 causes decrease in OS, CCA or CN



## SEPA 3. Data Discretization.

Endpoint Trend Assessment: Calculate an average perturbation value







## SEPA 3. Data Discretization.

Endpoint Trend Assessment: Calculate an average perturbation value





## **\$EPA**

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).



## **SEPA**

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).



## **\$EPA**

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).



## **S**EPA

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).

Discretized Trajectory of HepG2 after application of Butachlor at 200uM



### **Set EPA**

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).

Discretized Trajectory of HepG2 after application of Butachlor at 200uM



### **Set EPA**

# 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).

#### Discretized Trajectory of HepG2 after application of Butachlor at 200uM







# 5. Needleman–Wunsch optimal global alignment, and Error Estimation

Error in BN prediction was estimated as the sum of the Hamming distances\* between observed and predicted discretized trajectories.



\* The Hamming distance between two states is the number of positions at which the states are different

**EPA** 6. Coverage

#### I. Error Estimation is performed:

- 1. For each trajectory During this step we split BNs with the lowest error ("the baseline error") from BNs with higher error.
- Across all trajectories During this analysis we estimated the number of trajectories predicted by each BN with an accuracy ≤ to the baseline error ("coverage").

	trajectories						
	1	2	3	4	5	6	7
BN1	1	1	1	0	1	0	0
BN2	0	0	0	1	0	1	0
BN3	0	0	1	0	0	0	1

1 – BN covers traj.

0 – BN does not cover traj.

BN1 Coverage = 4 traj.

BN2 Coverage = 2 traj.

BN3 Coverage = 2 traj.

**II.** The smallest set of BNs that covers all trajectories was inferred by selecting BNs with the largest coverage.

**\$**EPA



I. Introduction

### II. Methods:

- 1. Dataset
- 2. Data standardization, and Noise Threshold  $(z_0)$ .
- 3. Data Discretization.
- 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).
- 5. Needleman-Wunsch (NW) optimal global alignment, and Error Estimation.
- 6. Coverage.

#### III. Results:

- **1.** Discretized Trajectories and Total Perturbation.
- 2. Clustering of discretized trajectories, Error Estimation, and Coverage (first 10 BNs).
- **3. Learned BNs in case of Butachlor.**

### **IV.** Summary



### 1. Discretized Trajectories and Total Perturbation

## Example: Butachlor - one of the most commonly used herbicides in agriculture.





### 2. Clustering of discretized trajectories, Error Estimation, and Coverage





Clustering

# 2. Clustering of discretized trajectories, Error Estimation, and Coverage



time [h]



### 2. Clustering of discretized trajectories, Error Estimation, and Coverage





### 3. Learned BNs in case of Butachlor

Butachlor 200µM







### 3. Learned BNs in case of Butachlor



**SEPA**







**SEPA**



I. Introduction

### II. Methods:

- 1. Dataset
- 2. Data standardization, and Noise Threshold  $(z_0)$ .
- 3. Data Discretization.
- 4. Learning Boolean Functions and Construction of Boolean Networks (BNs).
- 5. Needleman-Wunsch (NW) optimal global alignment, and Error Estimation.
- 6. Coverage.

### III. Results:

- 1. Discretized Trajectories and Total Perturbation.
- 2. Clustering of discretized trajectories, Error Estimation, and Coverage (first 10 BNs).
- 3. Learned BNs in case of Butachlor.

### **IV. Summary**



- 1. Response of HepG2 cells to concentration dependent chemical treatment shows three temporal trends: 1) no-effect, 2) adaptation, and 3) lack of recovery.
- 2. We have found that 573 BNs are needed to cover all trajectories.
- 3. BN with the greatest coverage explained 1,489 trajectories. These trajectories were produced by low treatment concentrations and we believe they represent cellular recovery processes.
- 4. Trajectories produced by high concentration treatments, that resulted in cell death, were predicted by a different set of BNs.
- 5. Our findings illustrate the utility of BNs that differentiate cellular programs involved in adaptation versus injury.



### Thank you